

The THINK Component-Based Operating System

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MDE for Embedded System - Brest, September the 6th to 10th 2004
<http://www.ensieta.fr/mda/>

Partly based on material from T. Coupaye

Overview



➔ I - THINK and CBSE

- Mastering software complexity
- Component-Based Software Engineering
- Expected benefits
- The THINK initiative

➔ IV - The THINK component library

- The library
- Supported hardware
- Typical composition
- Evaluations
- Kernel constructions

➔ II - Fractal component model

- Concepts
- Principles
- Organisation (open component model)
- APIs

➔ V - Conclusion

- Summary
- Links

➔ III - THINK, a Fractal support for Operating System

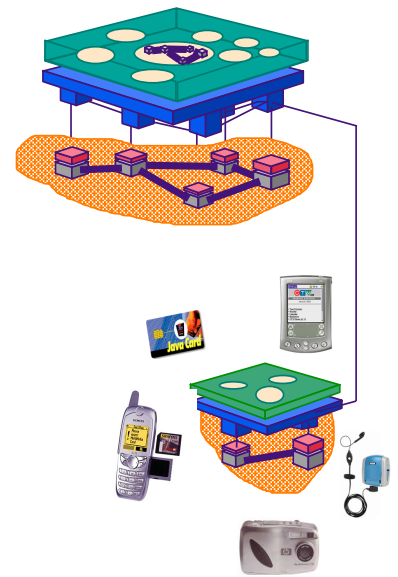
- Interfaces
- Components
- Development
- Configuration
- Deployment

Mastering Software Complexity



➔ The challenge of software engineering today is to conciliate

- the mastering of the
 - development
 - deployment
 - integration
 - management (operation)
 - evolution
- of software systems that are
 - distributed (asynchrony, faults)
 - heterogeneous (equipments, networks, OS, middleware, services)
 - open (topology, dynamicity)
 - partly legacy (third party elements)
- ... while taking into account applicative services needs (QoS)



➔ Where are we ?

- "The computer industry has spent decades creating systems of marvelous and ever-increasing complexity. But today, complexity itself is the problem" A. Ganek, T. A. Gorbi (IBM)
- "We don't understand something very fundamental about how we build systems" J. Hennessy (Stanford)

Component-Based Software Engineering



➔ CBSE is a broad effort towards the *rational construction* and *management* of complex software systems

➔ Preliminary definitions*

- "A **software component** is a software element that conforms to a component model and can be independently deployed and composed without modification according to a composition standard"
- "A **component model** defines specific interaction and composition standards"
- "A **component model implementation** is the dedicated set of executable software elements required to support the execution of components that conform to the model"
- "A **component infrastructure** is a set of interacting software components designed to ensure that a software system or subsystem constructed using those components and interfaces will satisfy clearly defined performance specifications"

*from G. T. Heineman, W. T. Council (eds.). Component-Based Software Engineering, Putting the Pieces 0. Addison-Wesley, 2001.

Expected Benefits of CBSE (1/2)



➔ Adaptation, integration and interoperation of software with bounded effort

- Arbitrary deployment environments
 - ↳ construction of dedicated software infrastructures (e.g. embedded operating systems)
- Evolution in needs, technical evolution
 - ↳ maintainability, durability
- Organizational evolutions
 - ↳ interoperation, integration
- Dynamic evolution
 - ↳ availability, scalability

➔ Management (administration)

- **Uniform control of software resources:** drivers, resources managers, pool, cache, network domain, process, service, ...
- Possibility to **instrument** resources - including dynamically and automatically

Expected Benefits of CBSE (2/2)



➔ ...more generally, prediction/assessment of certain *properties* (constraints) on software *composition/assembly*

- Reliability, correctness, fault-management, fault-tolerance
- Security, access control, isolation
- Scalability, Availability
- Testability, manageability, maintainability, durability
- QoS, real-time
- ...

NB: "Components are a way to impose design constraints that as structural invariants yields some useful properties" Conclusions of the 7th International Symposium on Component-Based Software Engineering (ICSE2004-CBSE7), Edinburgh, Scotland, May 2004

The THINK Initiative



➔ THINK Goals

- Build complex software by assembling, composing « software bricks » a.k.a. components
- Provide an *homogeneous vision* of operating systems topology
- No pre-defined kernel philosophy (e.g mono, micro, exo, ...)
- No pre-defined core functionality (scheduler, memory management, ...)
- Systematic use of components
- Hardware abstraction components provide direct access to hardware functions
 - Smaller one bring high portability

➔ Process

- Define *architectural principles* and *concepts* for the construction and management of software systems
- Realize *implementation* than can be
 - Extended
 - Toolled
 - Composed gracefully (communications, security, QoS, ...)

➔ Adopt the Fractal component model

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Fractal Concepts Overview

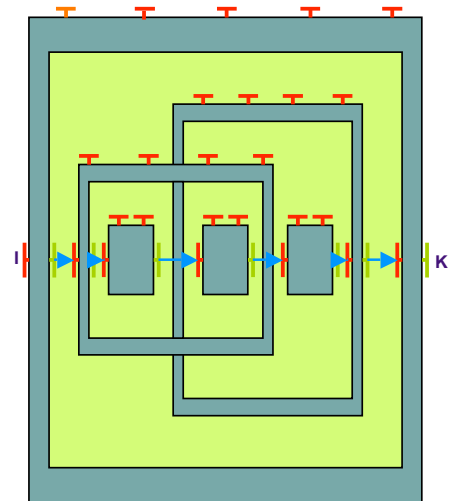


➔ « Classical » concepts

- › **Components** are runtime entities
- › **Interfaces** are the only access points to components. Interfaces emits and receives operation invocations
- › **Bindings** are communication channels. They can be primitive (in the same address space) or composite (to cross over boundaries). In the latter case, they are represented as components and bindings

➔ More original concepts

- › A component is the composition of a **membrane** and a **content**
- › The membrane exercises an arbitrary control over its content. A membrane is made of **controllers**. It can export control interfaces for some of these controllers
- › The model is **recursive** at arbitrary levels. The recursion stops with base components which have an empty content. Base components encapsulate entities in an underlying programming language
- › Components can be **shared** by multiple enclosing components



Components



➔ Definition

- › *A runtime entity exhibiting a recursive structure and reflexive capabilities...*

➔ Components as runtime entities

- › Components are units of
 - Development : design, modelling, implementation
 - Deployment
 - Packaging, installation, configuration, activation
 - Operation (administration)
- › Fractal targets the complete software life cycle but focuses on component as runtime entities
 - Components do exist and can be manipulated as such at runtime for operation purposes**

➔ No predefined « granularity »

- › Fractal components can be of any size
 - e.g. service, resource, data, protocol stack, packet network, binding (stub), drivers, threads, scheduler, ...

Interfaces



➔ Definition of (component) interface

- **An access point to a component**
- An interaction point between components
- A place where operation invocations can be emitted or received

➔ Not to be confused with *language interface* in relation with typing in Fractal

- Defined as a list of *operation signatures*, e.g. IDL interfaces
- Also called **interface signature** in Fractal typing
 - An *interface type* defines
 - an *interface signature*
 - some additional *properties (constraints)* (cardinality, contingency...)
 - Which maps ODP definition :
“An abstraction of the behaviour of an [component] that consists of a subset of the interactions of that [component] together with a set of constraints on when they may occur”

➔ Fractal terminology also uses

- Client versus server interfaces a.k.a role
 - A place where operation invocations can be emitted (client interface) or received (server interface)
- “Functional” versus “control” interfaces
- External versus *internal* interfaces (detailed later)

Bindings



➔ Abstract definition

- **A communication channel between components**
- Bindings are “oriented” from a *client* to a server *interface*

➔ Bindings are concretized as “*primitive*” or “*composite*” bindings

- (Primitive) binding : local communication channel between components (interfaces), i.e. in the same address space
 - (Primitive) Bindings are typically implemented by C pointers.
- Composite binding : a configuration of *binding components* and (primitive) bindings
 - Binding components : specialized component dedicated to communication between components to deal with :
 - Distribution : components not in the same address space
 - Communication styles : synchronous, asynchronous...
 - Other communication properties connected to proxy, security, transactions, etc.

Hierarchical Structure



➔ Fractal is hierarchical at arbitrary levels

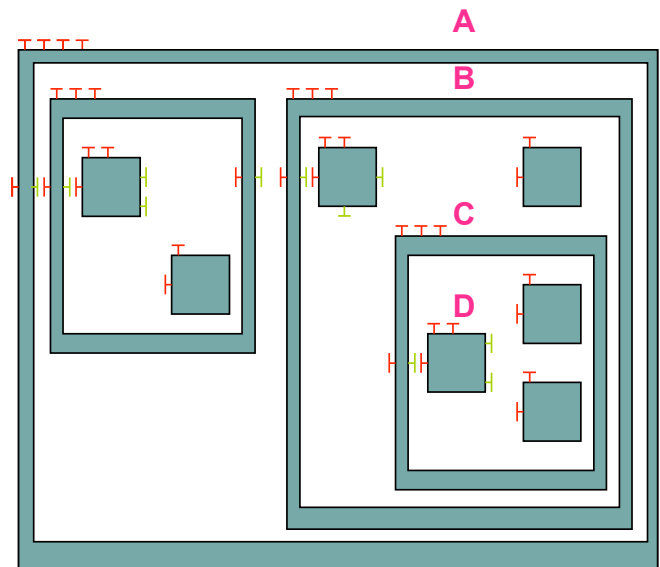
- Components as units of configuration
- A component controls the components it contains (a component is under the control of its enclosing component(s))

➔ Composite & primitive components

- A, B, C are composite
- D is primitive

➔ Sub and super relationship

- C is sub component of B
- C is super component of D



(Reflexive) Control



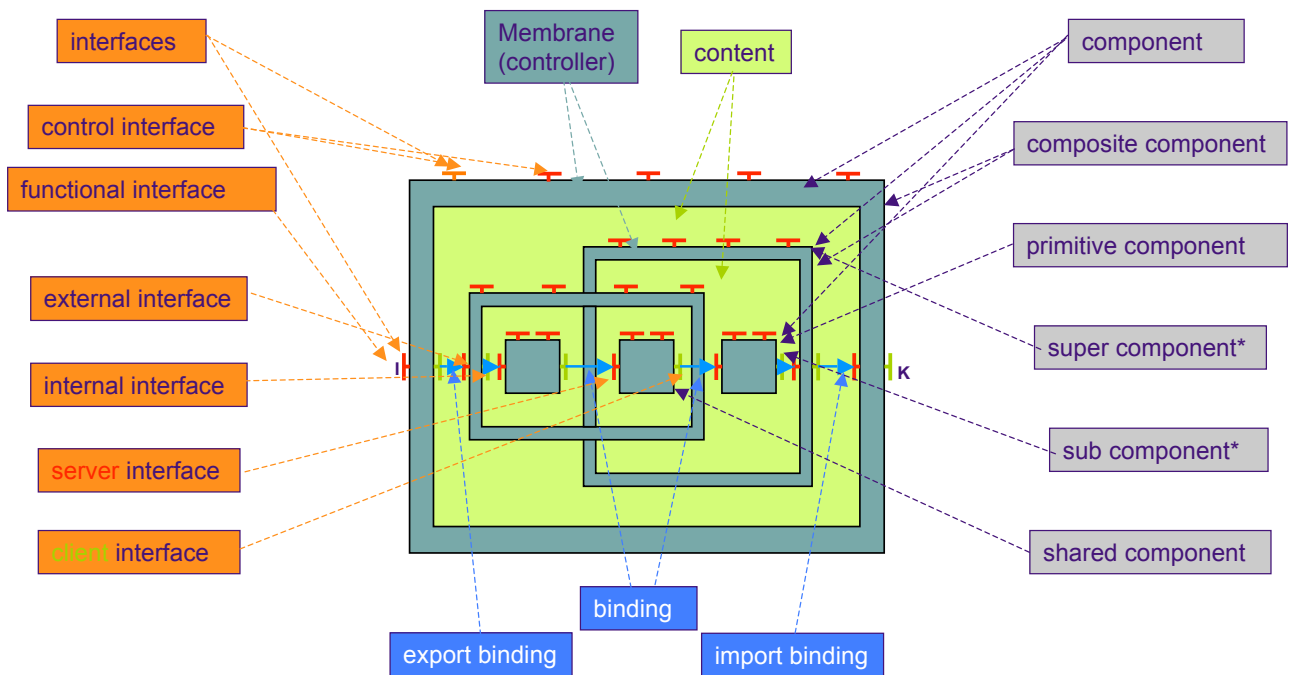
➔ Definition

- **A runtime entity exhibiting a recursive structure and reflexive capabilities. A component is composed of a membrane and a content. A component has well defined access points called interfaces, and provides more or less introspection and control (intercession) capabilities.**

➔ A membrane exercises an arbitrary control over its content. It embodies the control behavior associated to a particular component, e.g:

- It can provide explicit and causally representation of its content (sub components)
- It can intercept oncoming and outgoing operation invocations targeting or originating from its content an
 - Superpose a control behavior :
 - Suspending, check-pointing, resuming activities
 - Reifying or changing operation invocations parameters
 - Managing transparently technical services : persistency, security...
 - Managing QoS : memory consumption (garbage collection)...
- Or it can do nothing at all!

Structural Concepts and Terminology &



Architectural Principles



➔ Components as runtime entities

- Focus on deployment and **management** of open systems

➔ Separation between interfaces and implementations

- Interfaces are **the only access points** to components

➔ Programmatically controllable bindings

- Bindings are not static nor « hidden in code » but externalized so as to be manipulable by (external) programs

➔ Hierarchical structure with sharing

- Encapsulation, resource management

➔ Arbitrary reflexive control

- The specification only defines some predefined (“standard”) control interfaces dedicated only to structure management (except perhaps life cycle management ...)

Benefits



➔ For development

- The model enforces the use of « good principles »
 - Requires programmers to think about architecture
- Separation of concerns : functional vs non functional (management)
- Homogeneous development methods and tools
 - Modelling
 - Test
 - Debugging
- Reusability, portability

➔ For integration, deployment and administration

- Reusability (quick portability)
- Configurability (assemblage, parameterisation)
- Homogeneous administration tools (supervision, monitoring...)
- Reconfigurability, maintainability
 - Safety
 - Availability
 - Scalability
 - QoS

➔ Altogether

- More productivity for programmers
- More durability for software

Organization of the model



➔ Elements of the model specification

- « Levels of control »
 - Foundations
 - Base components with no reflexive capabilities (legacy code)
 - IDL : Fractal is not only for Java
 - Naming and binding API (Name, NamingContext, Binder)
 - Introspection
 - Component and Interface API
 - Introspection of components boundaries
 - Configuration
 - (structural introspection and intercession) Attribute, Content, Binding, Lifecycle control API
 - (Predefined but more generally arbitrary) reflexive control of (white-box) components structure
- Basic Typing : role, contingency (optional, mandatory), cardinality (singleton, collection)
- Instantiation
 - Generic factories : create components of a type given as input
 - Standard factories : “ad-hoc” factories that create components of one type each
 - Templates : “facilities” that create components isomorphic to themselves

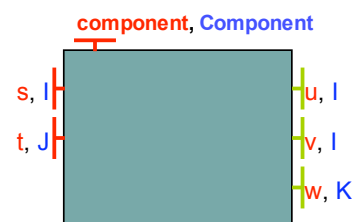
➔ Everything is optional and extensible (« open model »)

- Introspection, control interfaces and controllers, factory interfaces, typing

Introspection API



- ➔ This level provides external introspection capabilities
- ➔ A component at this level owns the **Component** Fractal control interface for interfaces discovery
 - **Component** allows discovery of all interfaces owned by a component (server and client, external and **internal**)
- ➔ Interfaces are named
 - The **name** of an interface is valid in the context of the component that owns this interface
- ➔ Interfaces are typed
 - An interface implements both
 - its functional interface signature (expressed in Fractal IDL: e.g. **I, J, K**)



```
interface Component {
    any[] getInterfaces ();
    any  getInterface (string itfName);
}
```

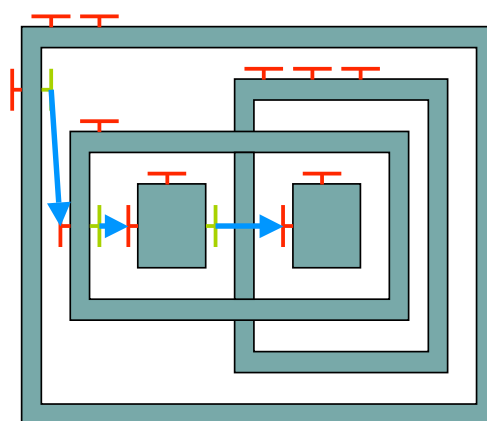
Configuration API (1/5)



- ➔ This level provides more introspection and intercession capabilities
- ➔ It allows for exposition and control of components internal structure
- ➔ It defines 5 « standard controllers » ...
 - BindingController
 - ContentController, SuperController
 - AttributeController
 - LifecycleController

...used for initial configuration and dynamic reconfiguration

- ➔ **NB**
 - Bindings and content controls are really central to *architectural configuration*
 - Attributes control is concerned with a restrictive, classical sense of configuration : parametrization
 - Stricly speaking, life cycle control is not concerned with configuration - but it often needed for configuration

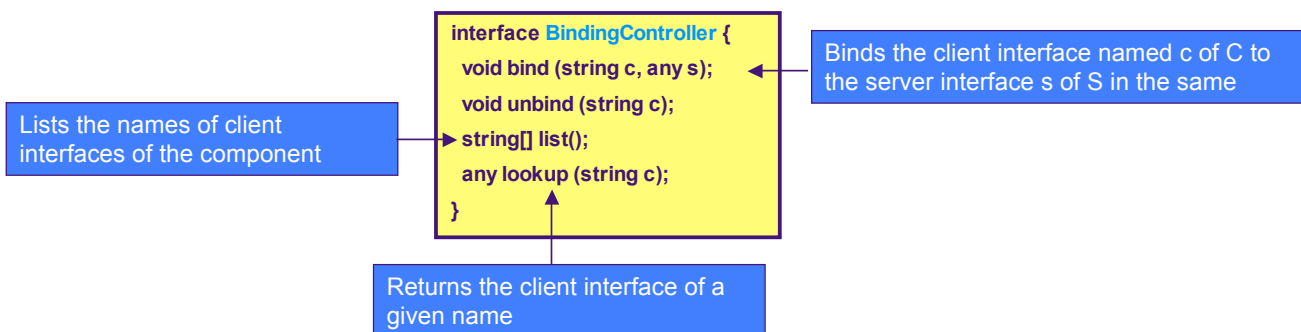
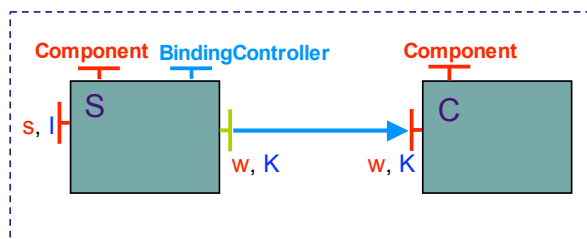


Configuration API (2/5)



➔ BindingController

- Used to manage *local bindings* between components
 - Complex bindings (e.g. remote)
 - Must be created using the naming and binding framework
 - May involve binding components
 - Strong semantics of *locality*
 - Bound interfaces must be owned by components in a same direct enclosing component

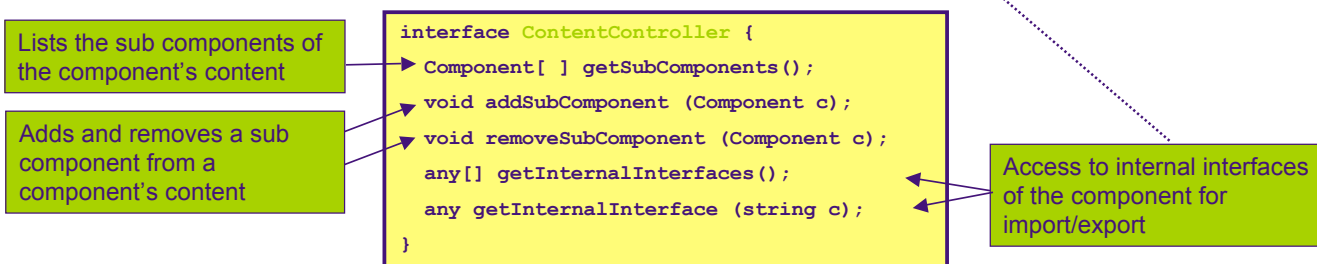
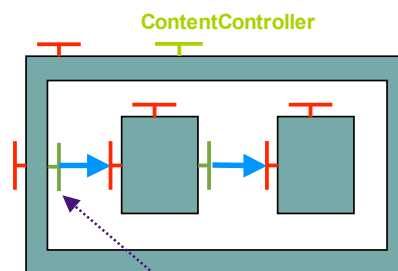


Configuration API (3/5)



➔ ContentController

- Used to manage the hierarchical structure of components
- Management of bindings between sub and super components (a.k.a. import/export bindings) belongs to content control



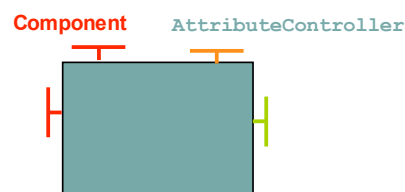
Configuration API (4/5)



➔ AttributeController

- Attributes are configurable properties of components
- AttributeController interface can be extended
 - Actually, only integer type managed

```
interface AttributeController {  
    int get(string attr);  
    void set(string attr, int value);  
}
```



Configuration API (5/5)



➔ LifeCycleController

- Semantics of start and stop are voluntarily as weak as possible
 - May implement usual suspend/resume or start/stop semantics
 - May or may not start/stop sub components
- The central point is the isolation of 2 states
 - STARTED in which components can accept operations only through their functional interfaces
 - STOPPED in which components can accept operations only through their control interfaces
- LifeCycleController will often be extended or completely redefined to suit arbitrary life cycles
- NB: this part of the specification may evolve and even disappear...

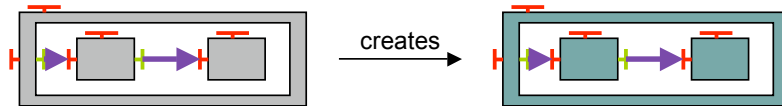
```
interface LifeCycleController {  
    void start();  
    void stop();  
}
```

Instantiation API



➔ Template

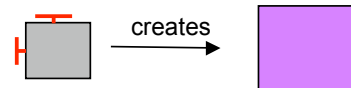
- › Component description
- › Can be instantiated many times
 - Statically (by compiler)
 - Dynamically (through generated factories)



➔ Factory

- › Dynamically create components of one specific type
 - They are explicitly programmed to do so
 - Or they are generated from template component description

```
interface Factory {  
    Component newInstance();  
}
```



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Interface Definition Language



➔ Interface Definition Language (IDL)

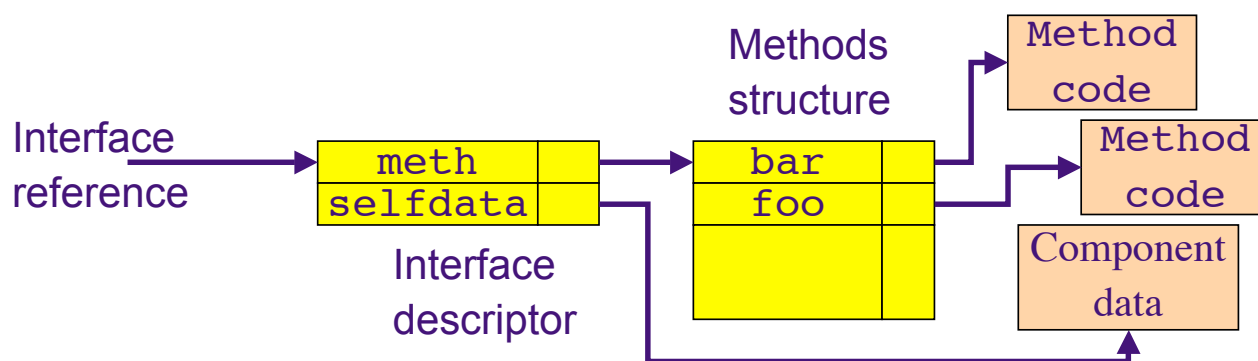
- Similar to ODP
- Interfaces are expressed with
 - Constant fields
 - Methods
 - Types
 - Primitives
 - [unsigned] {byte, short, int, long}, char
 - any
 - string
 - Interface references
 - Arrays
- Programming languages mapping
 - C
 - Primitive xxx ⇒ jxxx, unsigned xxx ⇒ juxxx
 - any ⇒ void*
 - string ⇒ char*
 - [] ⇒ *
 - ...

```
interface Test {
    int      bar(int arg);
    unsigned int foo();
}
```

Instantiation of interfaces



(cf. C++ Vtable)



```
interface Test {
    int bar(int arg);
    int foo();
}
```

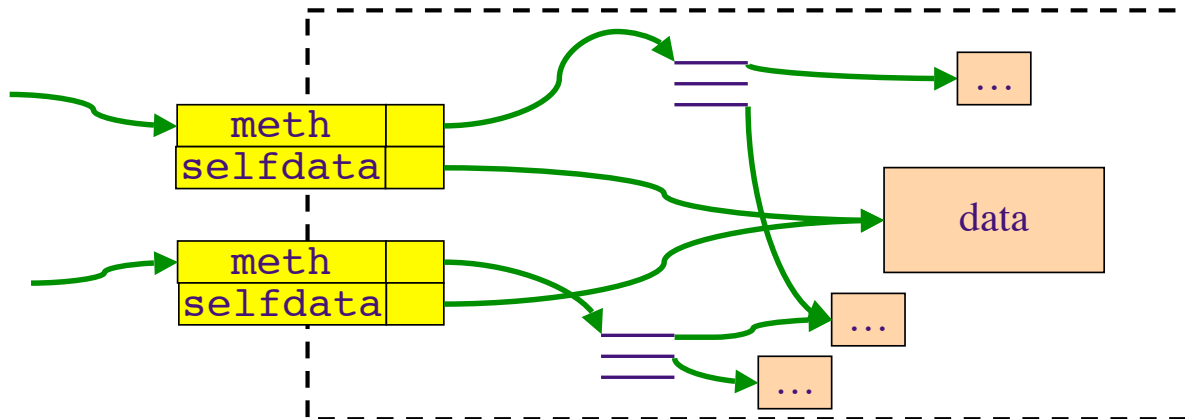
```
typedef struct {
    struct Mtest* meth;
    void *selfdata;
} RTest;
```

```
struct MTest {
    jint (*bar)(void* this, jint arg1);
    jint (*foo)(void* this);
};
```

Instantiation of components



➔ A component owns one or more functional interfaces



➔ Interface calling

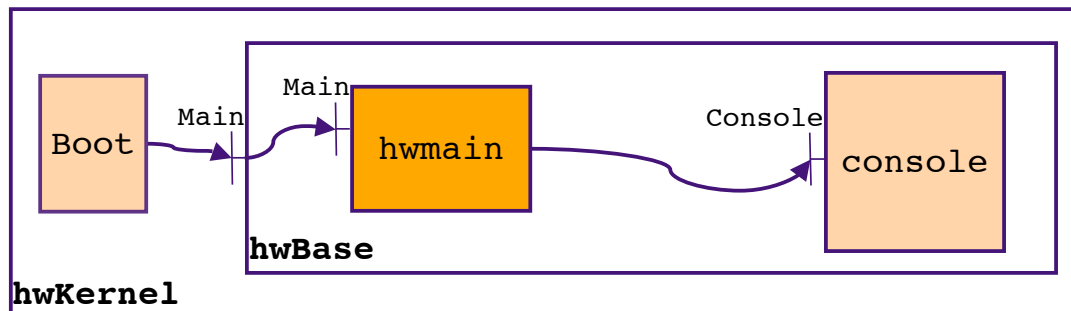
```
CALL(itf, proc, ...)
```

```
itf->meth->proc(itf->selfdata, ...)
```

Architecture Design



➔ The Hello World example



```
package activity.api;
interface Main {
    void main(int argc,
              string[] argv);
}
```

```
package video.api;
interface Console {
    void putc(char c);
    void puts(string str);
    void putxycs(int x, int y,
                string str);
    void scrollup();
    int cols();
    int rows();
}
```

Primitive ADL : hwmain



```
type MainType {
    provides activity.api.Main as main
}

type hwType extends MainType {
    requires video.api.Console as console
    attributes position
}

primitive hwmain implements hwType {
    skeleton hw nolifecycle
}
```

Can be mandatory,
optional or dynamic

or

```
primitive hwmain {
    requires video.api.Console as console
    provides activity.api.Main as main
    attributes position
    skeleton hw nolifecycle
}
```

Primitive implementation : hwmain



```
#include <activity/api/Main.idl.h>
#include <video/api/Console.idl.h>

struct hwmaindata {
    // Imported interfaces
    Rvideo_api_Console*    console;
    int    position;
};

#if ! defined(ONLYDEFINITION)

/* Main interface method */
static void mainentry(void* _this, jint argc, char** argv) {
    struct hwmaindata* self = (struct hwmaindata*)_this;
    CALL(self->console, putxycs,
        self->position,
        self->position, "Hello World !");
}

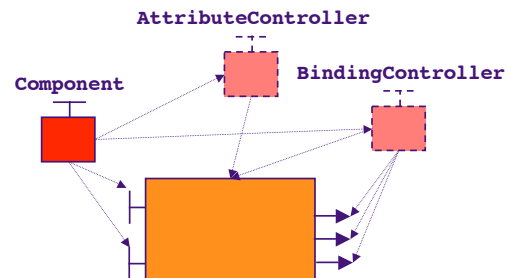
struct Mactivity_api_Main hwmain_mainmeth = {
    main: mainentry
};

#endif
```


Providing Fractal Configuration API &

➔ Either delegate configuration API implementation

- Generic shared tiny code
 - Works on meta-data which encodes internal & external behaviors extracted from ADL
 - Provided & required interfaces
 - Attributes
- Meta-data can be generated by tools
- Need to respect some programmatic convention naming



➔ Or implement our own

Delegation mechanisms &

```
struct exportedSkeleton {
    Rfractal_api_Component myreference;
    unsigned int nbexported;
    struct {
        char* name;
        struct { void* meth, *selfdata;} itf;
    } exported[];
};
```

```
struct importedSkeleton {
    unsigned int nbimported;
    struct {
        char* name;
        void* itf;
    } imported[];
};
```

```
/* BindingController delegation implementation */
static void bind(void* _this, char* name, void* itf) {
    struct importedSkeleton *self = _this;
    int i;
    for(i = 0; i < self->nbimported; i++) {
        if(strcmp(self->imported[i].name, name) == 0) {
            *(void**)(self->imported[i].itf) = itf;
            return;
        }
    }
    // Error: trying to bind an unexisting interface name
}

struct Mfractal_api_BindingController _bindingcontroller = {
    bind: bind,
    ...
};
```



```
#define ONLYDEFINITION

#include <hwmain.c>
static struct hwmaindata component2;
static struct importedskelton imported2 = {1, {
    {"console", &component2.console}}
};

static struct attributedskelton attributed2 = {1, {
    {"position", &component2.position}}
};

struct exportedskelton hwbase_hw = {
    {&_component, &hwbase_hw},
    3, {
        {"main", {&hwmain_mainmeth, &component2}},
        {"binding-controller", {&_bindingcontroller, &imported2}},
        {"attribute-controller", {&_attributecontroller, &attributed02}}
    }
};
```

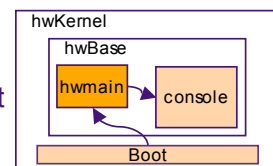
Composite component ADL



➔ No required code

➔ Describe

- Contents (which can be either primitive or composite component)
- Content bindings
- Content assigns
- Controller
 - A static tool (for generate required code) and a dynamic shared part
 - Existing controllers
 - Static - allows only static fixed configuration
 - Dynamic - allows dynamic reconfiguration (adding, removing, changing)
 - Secure - controls all interactions using a Reference Monitor



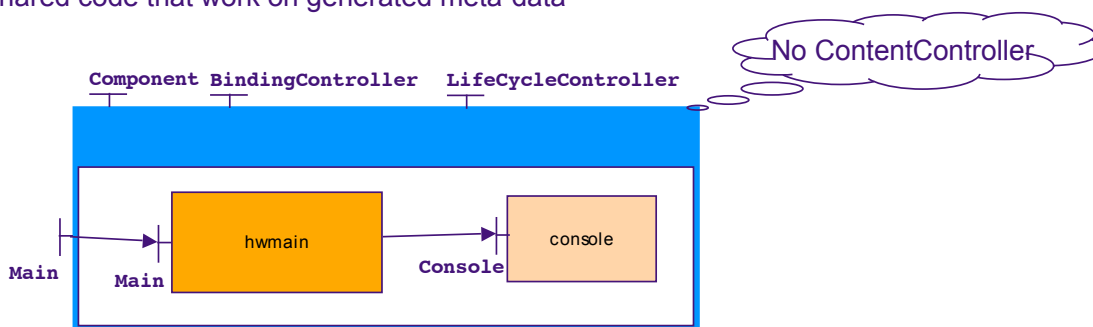
```
composite hwBase implements RootType {
    contains console = arm.sa1100.h3600.video.lib.screen
    contains hw = hwmain
    binds this.main to hw.main
    binds hw.console to console.console
    assigns hw.position = 3
    controller org.objectweb.think.controller.Static
}
```

Static controller



➔ Aims

- › Manages external bindings
 - No interception realized
- › Creates all sub-components
 - This phase was done statically
- › Binds sub-components together
 - By subsequent call to Component and BindingController of sub-components
 - A possible optimization was to fill statically dependencies on sub-component structures
- › Assigns sub-components attributes
 - By calling AttributeController of sub-components
- › Starts all sub-components
 - By traveling sub-components graph to respect order initialization
- › Shared code that work on generated meta-data

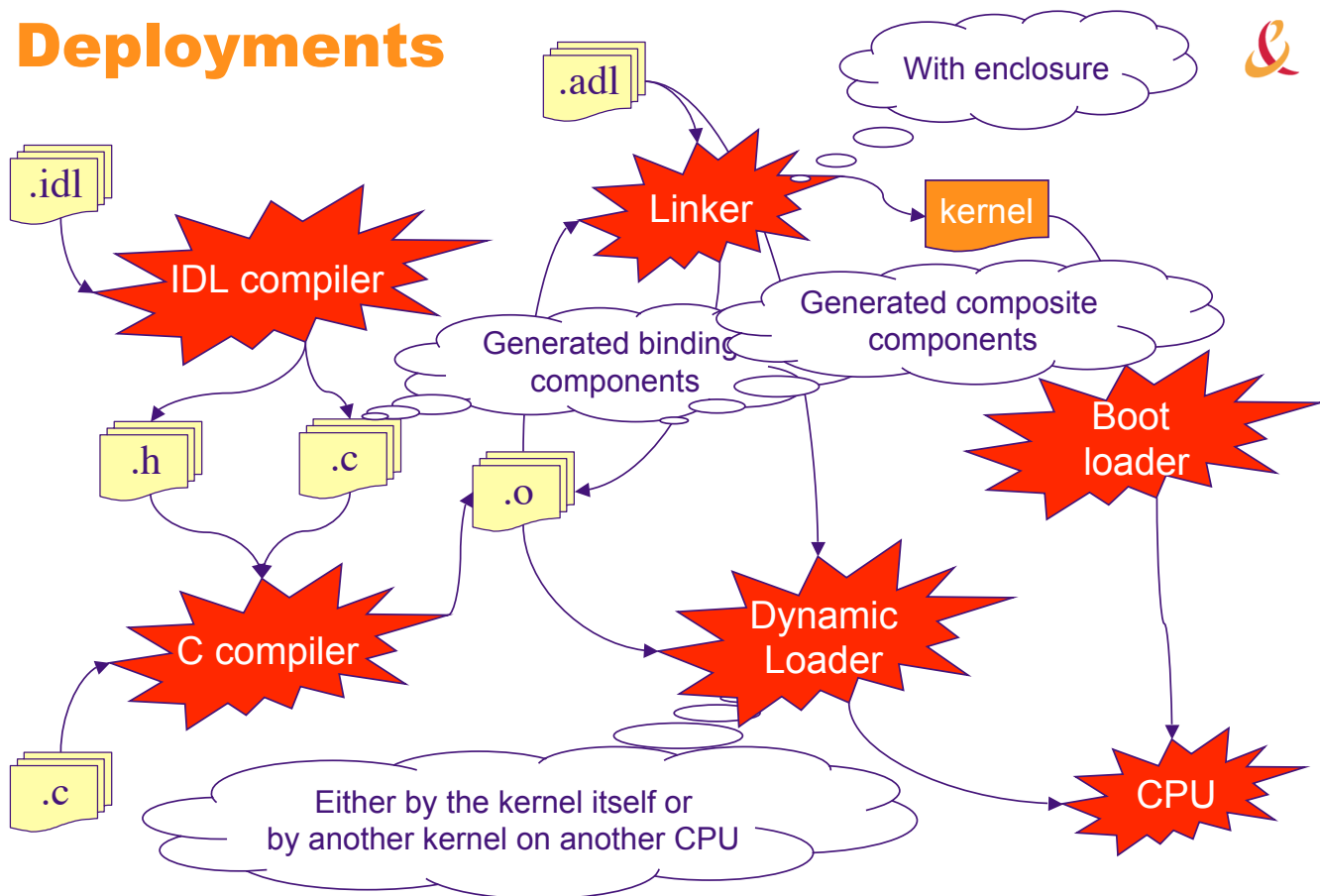


Generated meta-data : hwBase

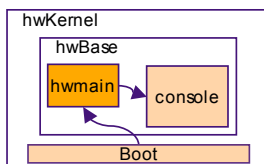


```
static struct bxmlcomponent kc1[] = {
    {&hwBase_console.myreference, NeedStart},
    {&hwBase_hw.myreference, NeedStart},
};
static struct bxmlbinding kb1[] = {
    {1, 0xff, Mandatory, "main", "main"},
    {0, 1, Mandatory, "console", "console"},
};
static struct bxmlattribute ka1[] = {
    {1, "position", (void*)(3)},
};
static struct ecdata hwBase = {
    sizeof(kc1) / sizeof(kc1[0]), kc1,
    sizeof(kb1) / sizeof(kb1[0]), kb1,
    sizeof(ka1) / sizeof(ka1[0]), ka1,
    {&_ECci, &hwBase},
    {&_ECbc, &hwBase},
    {&_EClcc, &hwBase},
};
```

Deployments



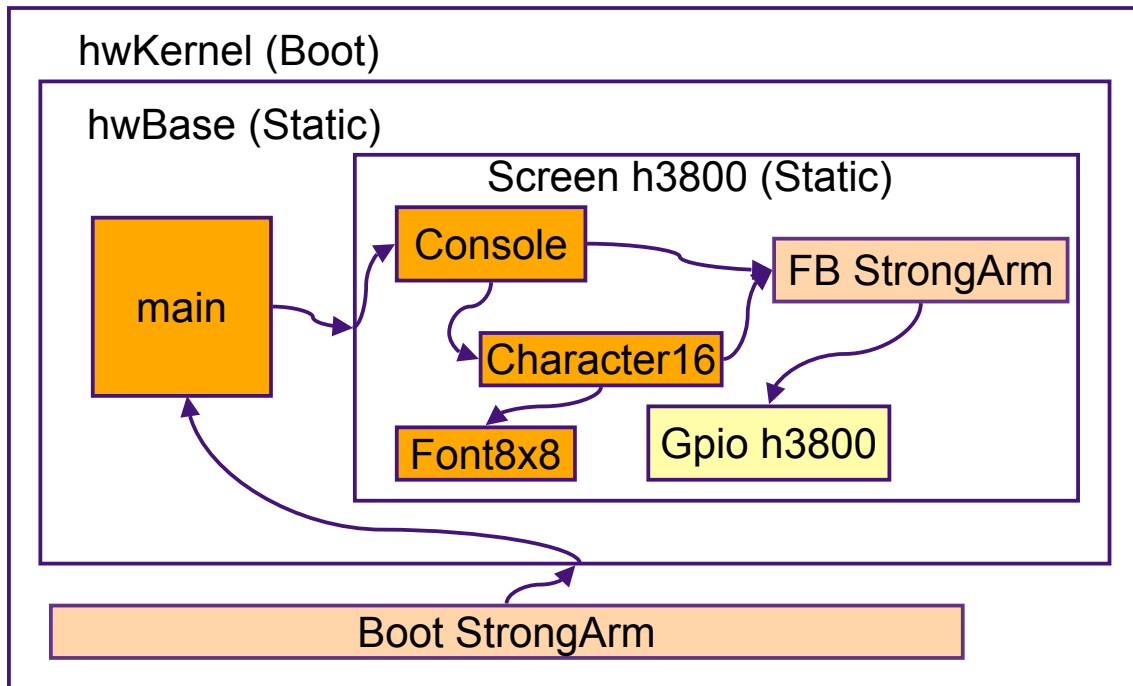
Final composition : hwKernel



```
composite hwh3600kernel {
  contains boot = arm.sa1100.boot.lib.boot
  contains main = hwBase
  controller org.objectweb.think.controller.Boot
}
```

```
composite hwh3900kernel {
  contains boot = arm.pxa.boot.lib.boot
  contains main = hwBase
  overloads main/console = arm.pxa.h3900.video.lib.screen
  controller org.objectweb.think.controller.Boot
}
```

“Hello World” for iPaq h3800



Overview



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- › Component-Based Software Engineering
- › Expected benefits
- › The THINK initiative

➔ II - Fractal component model

- › Concepts
- › Principles
- › Organisation (open component model)
- › APIs

➔ III - THINK, a Fractal support for Operating System

- › Interfaces
- › Components
- › Development
- › Configuration
- › Deployment

➔ IV - The THINK component library

- › The library
- › Supported hardware
- › Typical composition
- › Evaluations
- › Kernel constructions

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- › Links

The KORTEX library



➔ Hardware abstraction components (HAL)

- Boot
- Exceptions (PIC, timer, ...)
- MMU (page table, TLB, exceptions, ...)
- Cache
- Device drivers
 - Human devices: frame-buffer, keyboard, touch panel, ...
 - Storage devices: Disk, Flash
 - Communication devices: Serial port, Ethernet, Bluetooth

➔ Operating system services

- Memory management components (flat & paged memory)
- Thread and scheduler components (cooperative, round-robin, priority, QoS)
- Network components (x-kernel)
 - Ethernet, IP, TCP, UDP, SunRPC
- Bluetooth components
 - HCI, L2CAP, RfComm, HDI, Obex
- File system components (VFS API)
 - JFFS2, E2FS, NFS, Ramdisk
- Binding components (local & remote communication)
- Service components (process, dynamic linker/loader, trader, ...)
- Posix components (for application portability)

Supported Hardware



➔ Conform with Fractal components model

- PowerPC G3 / G4
 - Apple Power Macintoshes (Only New-world architecture)
- ARM
 - Intel StrongARM (HP/Compaq h3600, h3800)
 - Intel xScale (HP/Compaq h3900, h2200, h5500)
 - Portal Player's PP5002 (Apple iPod)
 - Motorola Dragon Ball MX 1

➔ Experimentations (past and future)

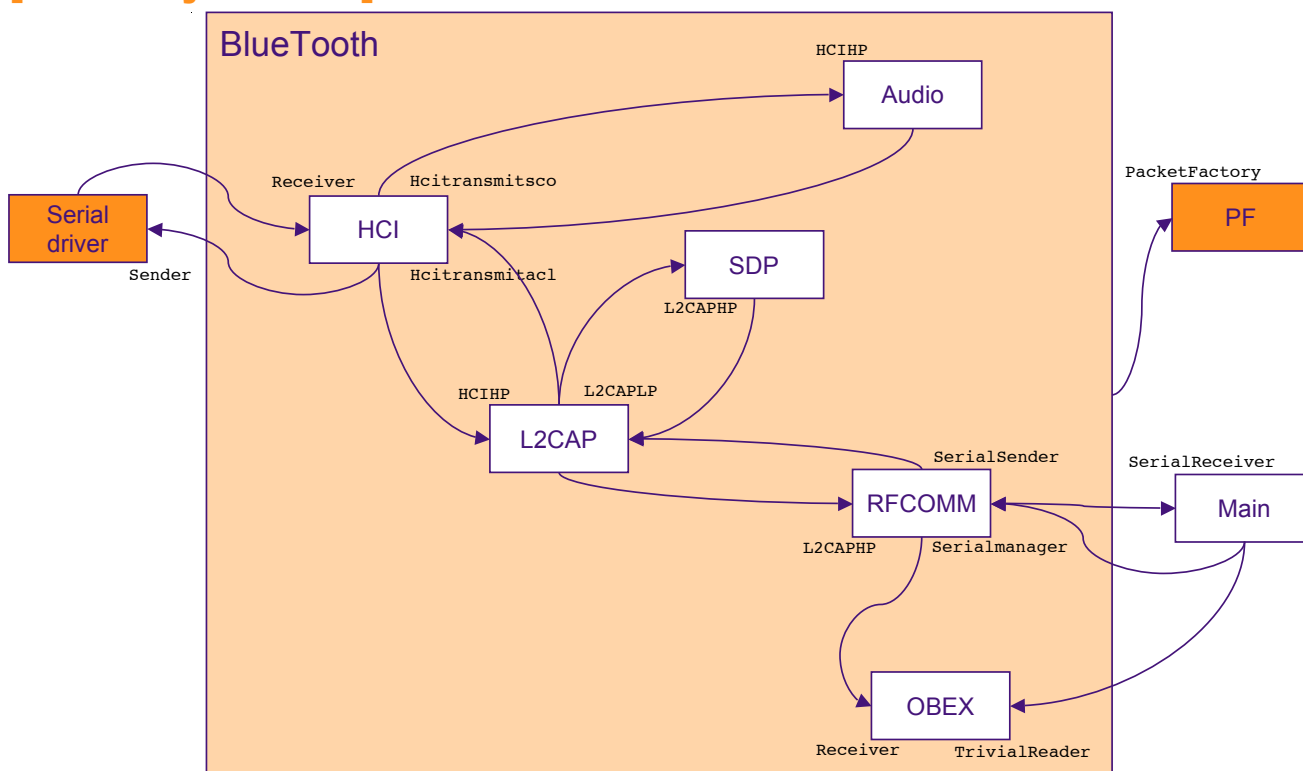
- PC (Intel x86) [INRIA]
- Lego RCX (Hitachi H8 16Mhz, ROM 16KB, RAM 32KB) [INRIA]
- Tini Internet Interface (microcontroller DS80C390, ROM 512KB, RAM 1MB) [INRIA]
- DSP [ST Microelectronics]

➔ Simulator

- HAL components built on Unix (Linux, Mac OS X, Cygwin)
- Run Think kernels on Unix processes
 - Porting and debugging purpose

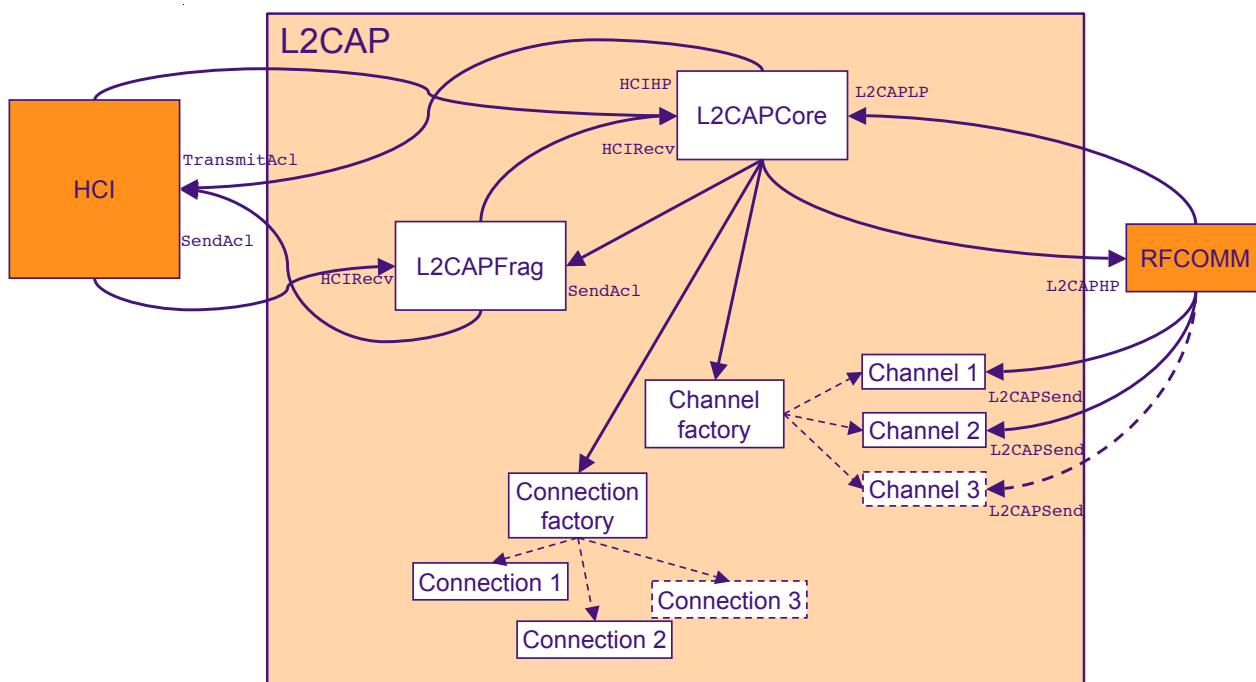
Bluetooth (1)

[Anthony Pellerin]



Bluetooth (2)

[Anthony Pellerin]



Scheduling interfaces



```
interface Scheduler {
    void initJob(Job job,
                byte* function,
                byte* stackbase,
                int stacksize,
                int arg);

    void destroyJob();
    void addJob(Job job);
    void removeJob(Job job);
    Job getJob();
    void yield();
}
```

```
interface Semaphore {
    void P();
    int tryP();
    void V();
}
```

```
interface Job {
    void run();
    void enqueue (Job* jobqueue);
    void dequeue ();
    Job getQueue ();
    byte* getContext();
    void activate();
    MMUSpace getSpace();
}
```

```
interface Mutex {
    void lock();
    int trylock();
    void unlock ();
}
```

Component sizes



	Sub components	Size (KB)
Limited TCP/IP stack	9	15.5
Console & graphic drawer	9	9
H3900 frame buffer (including video memory)	1	160
H2200 frame buffer (video memory on controller)	1	0.9
Preemptive priority scheduler & semaphore	11	5.7
ARM cache & flat memory management	7	3.9
Think controllers	4	3.1
C runtime (sprintf, str _{xxx} , mem _{xxx} , divsi3, ...)	n.a.	7.7
ARM EFL dynamic components loader	4	2.2
JFFS2 flash reader	3	9.1
PXA serial port & ymodem	2	1.7
H3900 touch panel	5	3.9
Bluetooth stack (HDI, RFCOMM, OBEX, ...)	17	83

Performance overheads



➔ After configuration, only interface calls add overhead

➔ Interface calling overhead

```
itf->meth->foo(itf->data);
Void fooimpl(void* _this) {}
```

➤ ARM

	Instruction
Interface calling	5
Procedure calling (with context)	3
Procedure calling (without context)	2

➤ PowerPC

	Instructions	Time	Cycles
Interface calling	6	0.016 μ S	8

Memory footprint overheads



➔ Primitive components

	Delegation overheads (bytes)	Optimized controller (bytes)
Exported interfaces	$4 + 12 * n$	$8 * n$
Imported interfaces	$4 + 8 * n$	0
Attributes	$4 + 8 * n$	0

➤ For the 3KB IP component, overhead is about 2%,

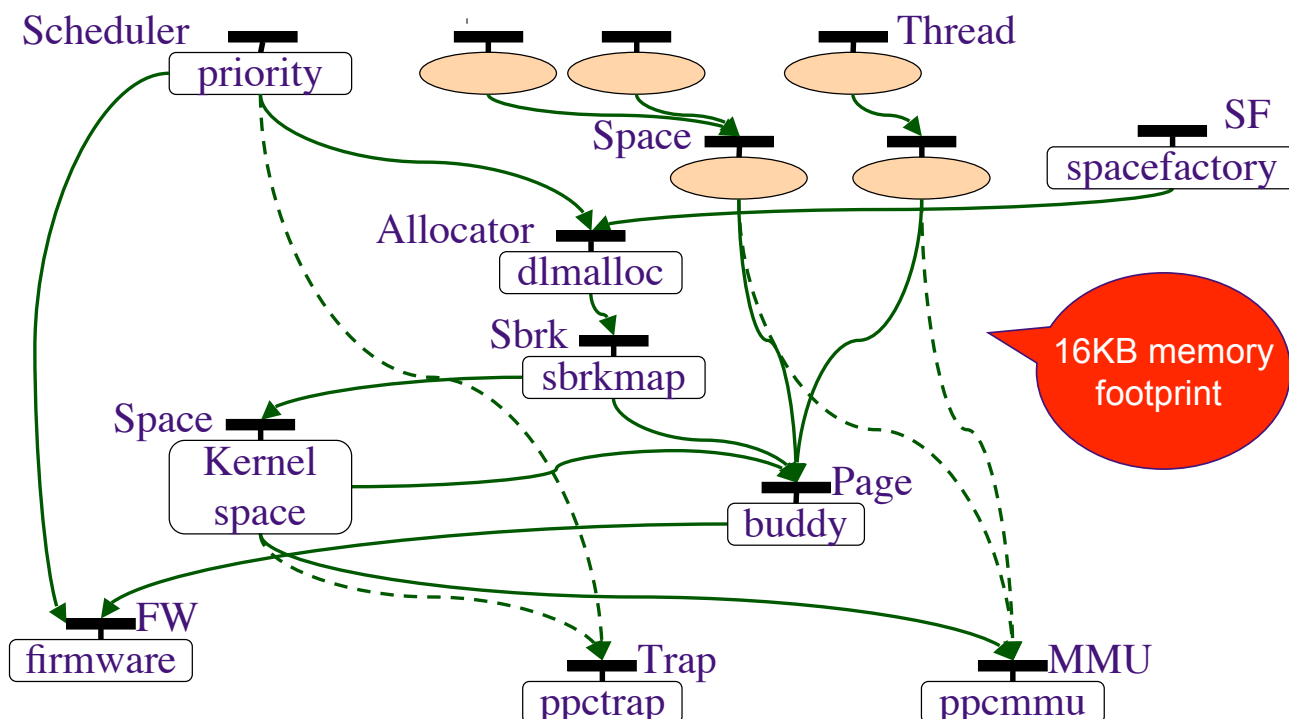
➤ For a 1 KB frame buffer, overhead is about 6%.

➔ Composite components

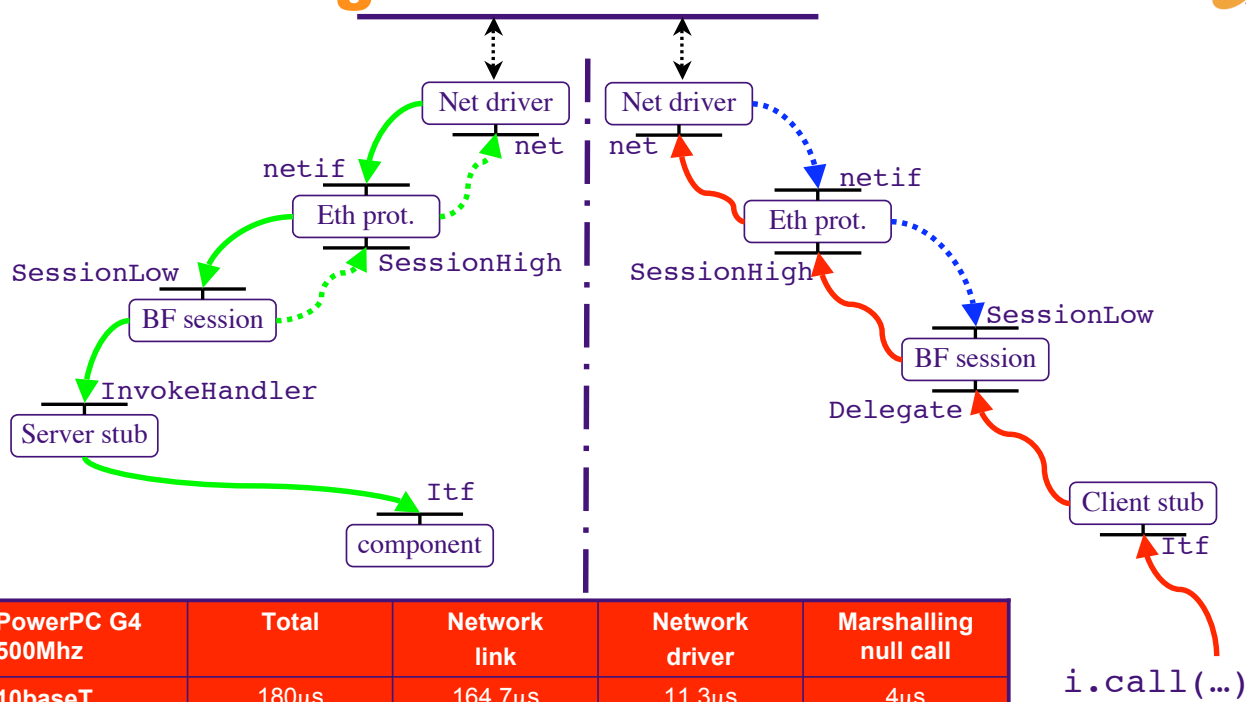
	Standard controller (bytes)	Optimized controller (bytes)
Sub components	$4 + 8 * n$	0
Sub bindings	$4 + 12 * n$	0
Attribute assigns	$4 + 12 * n$	0

➤ For the TCP/IP stack with 10 sub-components and 25 sub-bindings, overhead is near 400bytes.

Building a simple μ -kernel



RPC binding



PowerPC G4 500Mhz	Total	Network link	Network driver	Marshalling null call
10baseT	180 μ s	164.7 μ s (91.5%)	11.3 μ s (6.3%)	4 μ s (2.2%)
100baseT	40 μ s	24.7 μ s (61.7%)	11.3 μ s (28.3%)	4 μ s (10%)

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Conclusion



➔ Effectiveness of component model for building component-based operating system

- "Component-based" does not mean "less efficient"
 - Interface cost == C++ virtual cost
- Operating system development simplification
 - Components and interfaces clearly identified
- Quick system deployment
 - "Lego-like" construction of software by assembling pieces a.k.a. components
- Memory footprint reduction and performance increase
 - Removing unused services
 - Fine resources access allowed

➔ Yes, that works

Links



➔ Think home page

➤ <http://think.objectweb.org>

➔ Fractal home page

➤ <http://fractal.objectweb.org>

➔ Questions ?